

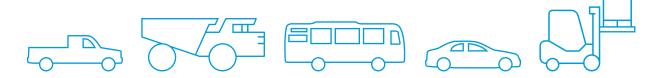
# M580-24V OpenECU<sup>™</sup> EV Supervisory Control

## Versatile

- Designed to meet ISO 26262 ASIL D functional safety requirements
- 112 pins of flexible I/O
- Integrated charging interface circuitry
- Truly open application-independent Simulink<sup>®</sup> development environment



Ideal for light, commercial and off-highway vehicles.



## M580-24V OpenECU<sup>™</sup> EV Supervisory Control

### **High Performance**

- Powerful NXP SPC5746 microprocessor and 4x CAN 2.0 channels
- Multiple H-bridges, low side drives and high side outputs
- Comprehensive fault diagnosis supporting functional safety as well as OBD requirements
- High level diagnostics fault reporting resident in platform software

### Capable

- Designed for complex hybrid and EV applications
- High-quality rugged hardware designed for engine compartment mount
- Supports common calibration tools such as ATI Vision, ETAS INCA, and Vector CANape via CCP
- Same proven hardware used for development can be used for volume production
- ISO 15118

Capabilities			
Highlights		I/O Summary	
Processor	SPC5746	Sensor Supplies	2x 5V @ 200mA
Clock Rate	160 MHz	Input Pins	40
Code Space	up to 3MB	Output Pins	44
RAM Space	up to 256kB	External Communication	4 x CAN 2.0 to main micro,
Calibration Space	up to 256kB		1x CAN to Secondary
Secondary Processor	SPC560P34	Outputs	
Clock Rate	64MHz	H-Bridges	1x 10A, 2x 5A, 1x 3.2A
Total Flash Space	up to 192KiB	Low Current Low Side Drives	10x 100mA, 3x 400mA,
Total RAM Space	up to 12kB		14x 700mA, 2x 1A
Inputs		High Current Low Side Drives	4x 2.2A, 1x 3.2A
Digital Inputs	9x switched, 3x PWM	High Side Outputs	2x 700mA
Analog Inputs	28	Physical	
Internal Features		Dimensions	225x205x45mm (WxDxH)
Partial Networking		Material	Aluminum
Wake on CAN (2 channels)		Weight	1.1kg
Wake on digital/PWM input		Connectors	Molex 112pin (1x48, 2x32)
Pilot and CC2 pins		Vibration	ISO 16750 chassis mount
Application		<b>Environmental Protection</b>	IP69K Sealed / Gore Vent
Location	Chassis/Passenger Compartment		
Supply Voltage	6.5 - 32V		

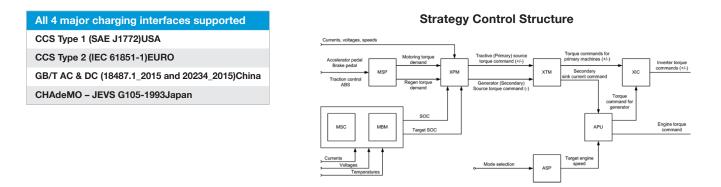
The M580 OpenECU is designed to support the most demanding EV supervisory control applications. Since most supervisory controls demand the highest level of functional safety, the M580 was developed using ISO 26262 processes.

The high performance SPC5746 microprocessor supported by the powerful 32-bit SPC560P34 secondary microprocessor provides for sophisticated, high-bandwidth rationality checking and system safety monitoring of full-authority vehicle control applications.

The M580 is designed to support EV supervisory control applications worldwide, the integrated charging circuitry eliminates the need for a separate charger interface module (Charging interface control application software not included.)

Due to its high quantity of customizable I/O, advanced microprocessor, safety oriented architecture and user friendly OpenECU<sup>™</sup> Simulink application interface, the M580 is a great rapid prototyping platform for a broad range of applications.

Dana also offers a full set of model based strategies suitable to support most EV / NEV architectures allowing it to be taken all the way into production. Dana systems, controls and software engineers are available to support application implementations from prototype to production.



#### OpenECU.com

#### Application Policy

Capacity ratings, features, and specifications vary depending upon the model and type of service. Application approvals must be obtained from Dana; contact your representative for application approval. We reserve the right to change or modify our product specifications, configurations, or dimensions at any time without notice.

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